



Defense Science & Technology Smart Sensor Web

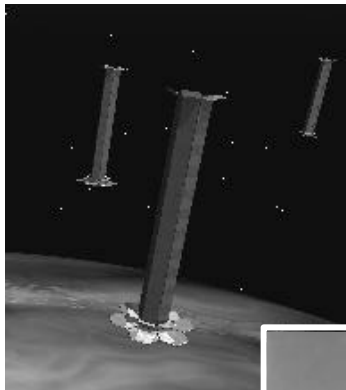
LTC Bruce L. Gwilliam, USA, Special Projects Officer
Office of the Deputy Under Secretary of Defense (Science & Technology)
Presentation to NDIA, October 12, 2000

DoD Science & Technology Mission

*To ensure that the
warfighters today and
tomorrow have
superior and
affordable technology
to support their
missions, and to give
them revolutionary
war-winning
capabilities.*



Future Revolutionary Capabilities



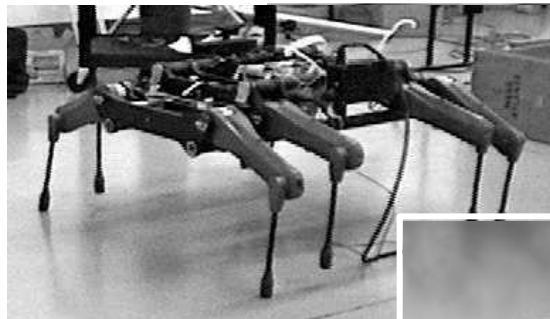
Microsatellites



Joint Strike Fighter



Micro Air Vehicles



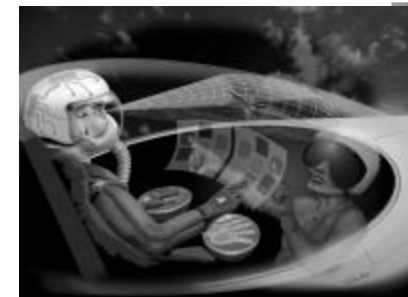
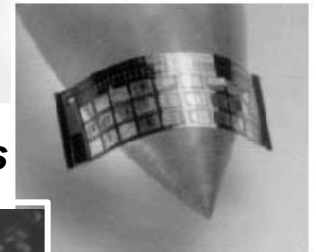
Micro Robots



DD-21



Flexible Sensor Skins



Augmented Reality

Bio Sensors



Embedded Biofluidic Chips



DUSD (S&T) Priorities (2000)

- Basic Research
 - Five Focus Areas
 - Chemical & Biological Defense
 - Information Assurance
 - Hardened & Deeply Buried Targets
 - Smart Sensor Web
 - Cognitive Readiness
 - Cross Cutting Initiatives
 - Software Intensive Systems
 - High Performance Computing
 - Modeling and Simulation
 - Technology Transition Watch/Exposition
 - S&T Pilot Laboratory Program
- 
- A faint, grayscale background image featuring the stars and stripes of the United States flag. In the lower right corner, there is a silhouette of an eagle with its wings spread, perched on a branch.

Smart SensorWeb

Complete Situation Awareness

Real-time Imagery

Micro-Weather

Moving Targets

Integration

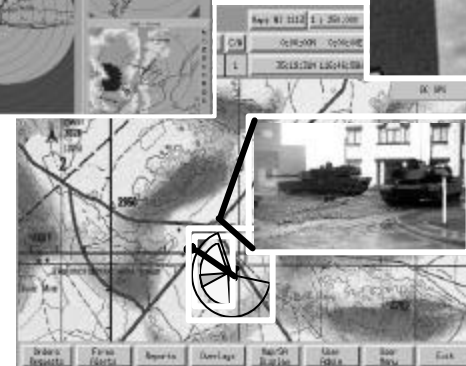
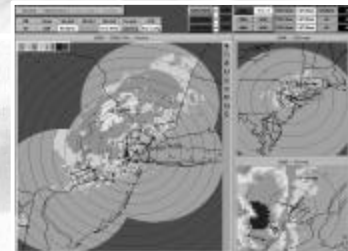
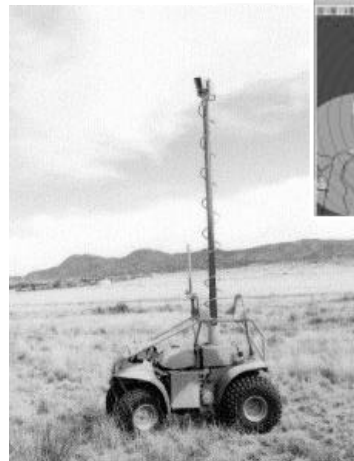
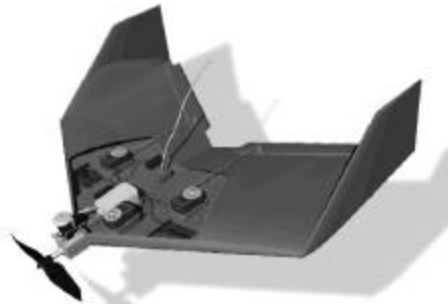
Physical Models

Dynamic Data Bases

Micro Sensors

Wireless Communications

Next Generation Internet

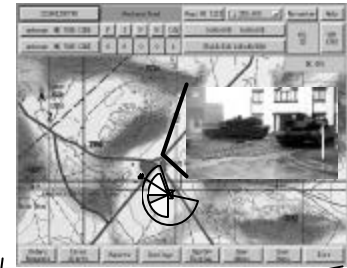


DoD Science & Technology

Smart SensorWeb

Vision: An intelligent, web-centric distribution and fusion of sensor information . . . that provides greatly enhanced situational awareness, on demand, to Warfighters at lower echelons.

“... emphasizes large arrays of local sensors joined with other assets: imagery, weather, weapons, simulations, etc. . . .”



- Enhanced situational awareness
- On-demand intelligent information
 - Images, weather, weapons, etc.
- Available to lower echelons
- Rapid weapon response

Smart SensorWeb

Local Situational Awareness Through Netted, Processed,
Low Cost Sensor Arrays

Smart SensorWeb

Sensor Technologies

TV
Uncooled Thermal
LADAR
Weather
Acoustic
Magnetic
COTS/MOTS

Enablers

MEMS
ATR
Computers
Sensor Fusion
Displays
Wireless
Networks
Robotics
GPS

UGV/
UGS



HMMWV



LOCAAS



HMD

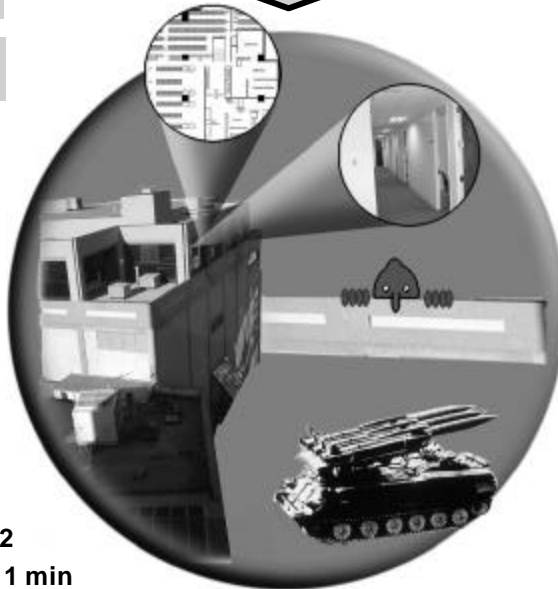


U UAV



Small Areas £ 1km²
Response Times £ 1 min
Locations Errors £ 1 mil
Spatial Resolution £ .3 m

Resolution Time



Unique SSW Capabilities

- Urban Canyons
- Subways, Sewers
- Difficult Rural Terrain
- Heavily Forested Areas
- Track Slow & Fast Objects
- Rapid Response Time

Current ISR

Sensor Technologies

Enablers

Data Links
ATR
Hi Perf Comp
UAV
MIMC
GPS

SAR, IFSAR

GMTI

HRR

Cooled Thermal

LADAR

Panchromatic

Spectral

Large Areas £ 100 km²
Response Times £ 1 min
Locations Errors £ 1 km
Spatial Resolution .3 - 30m

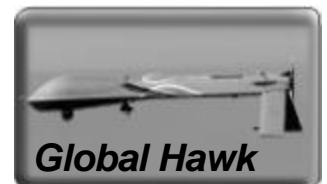
NTM DI



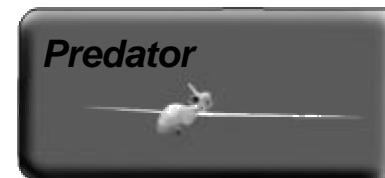
LRAS



Global Hawk



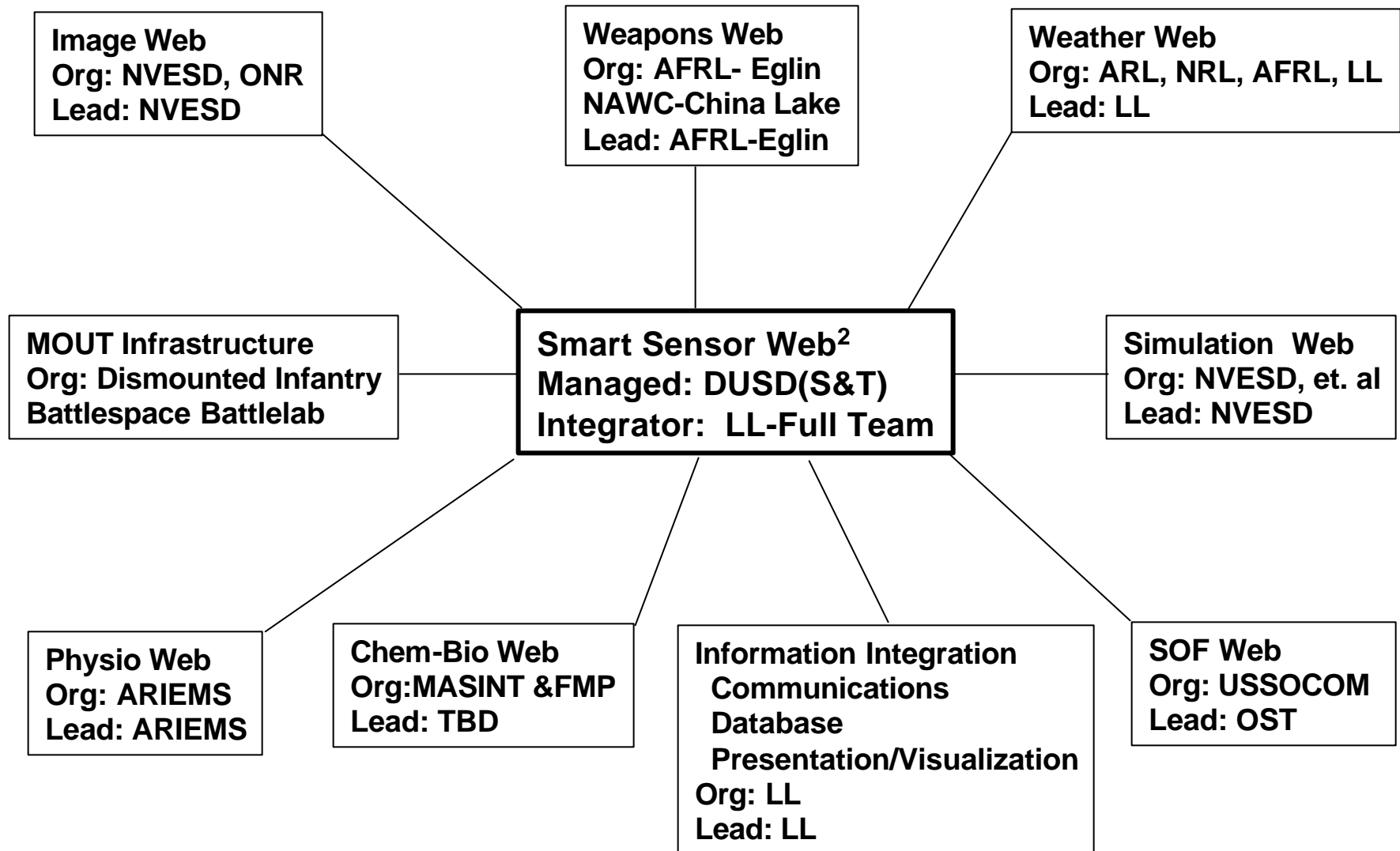
Predator



JSF



Technical Structure



IR Micro Camera Program



- **UL3: Ultra low cost FLIR for day/night imaging:**
 - 90 Grams (including optic)
 - 600 mW @ 3.5V
 - Development complete in July 00

Detection of Walking Man Target

FPA	Sensor Field of Regard/Range	
	40° FOV	15° FOV
160x120	FOR = 164m/ Range= 240m (165m)	167m/ 640m (440m)
320x240	328m/ 480m (330m)	334m/ 1280m (880m)

**Assumes Line of Sight.
Issue: Terrain Complexity
vs. Camera Range/Cost**

Target: Walking Man (0.75m/2.0° C)
50% (70%) Detection/0.75 cycles on target
Atmosphere: 80%/km

Examples of Mini-UAV Projects

Organic Small Unit Capability

Surrogate UAVs Candidates



CAMCOPTER

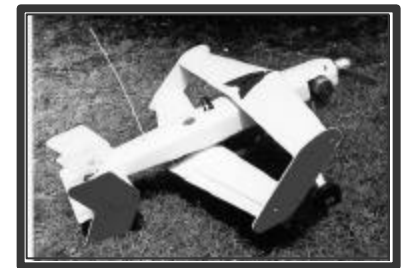
- Commercial UAV
- Thermal sensor



Para-Eyes (NVESD/NRL)



Mini Air Vehicles (DARPA)



Back Pack (NVESD FY00 Congressional Plus Up)

Wingspan	14.7 sq ft chute	36 inches	36 inches
Max TO Weight	6.5 lbs	2.25 lbs	25 lbs
Payload Weight	0.7 lbs	0.56 lbs (9 oz)	8 lbs
Sensor	120 x 160 CCD 240 x 320 (Growth)	CCD 240 x 320 (Growth)	CCD 240 x 320 (Growth)
Fuel	Battery	Battery	Oil/Alcohol or MOGAS

**NVESD /AATD/AMCOM MOU to Develop
an Integrated Sensor w/ Mini-UAV**

LOCAAS Characteristics

Guidance Integrated
Safe/Arm and Fuzing

- Optimal Fuzing Time
- Aimpoint Selection

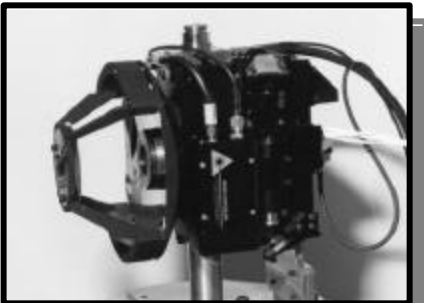
INS/GPS

- Midcourse Guidance
- Flexible Search Pattern



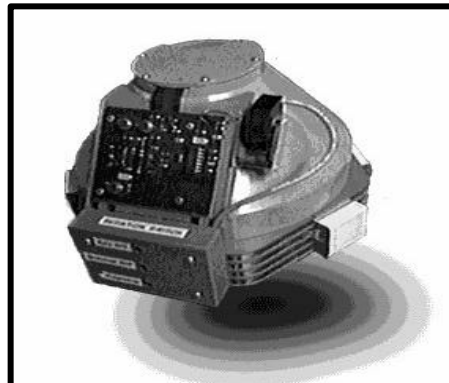
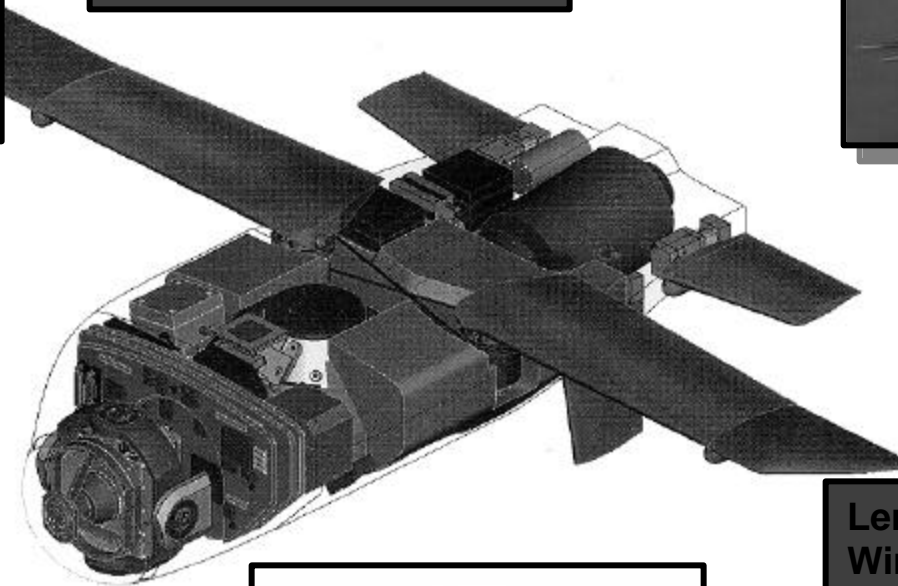
Miniature Turbojet

- Standoff Range
- Large Search Area



Solid State LADAR Seeker

- Large Field of Regard
- Autonomous Target Acquisition
- Simplified Mission Planning

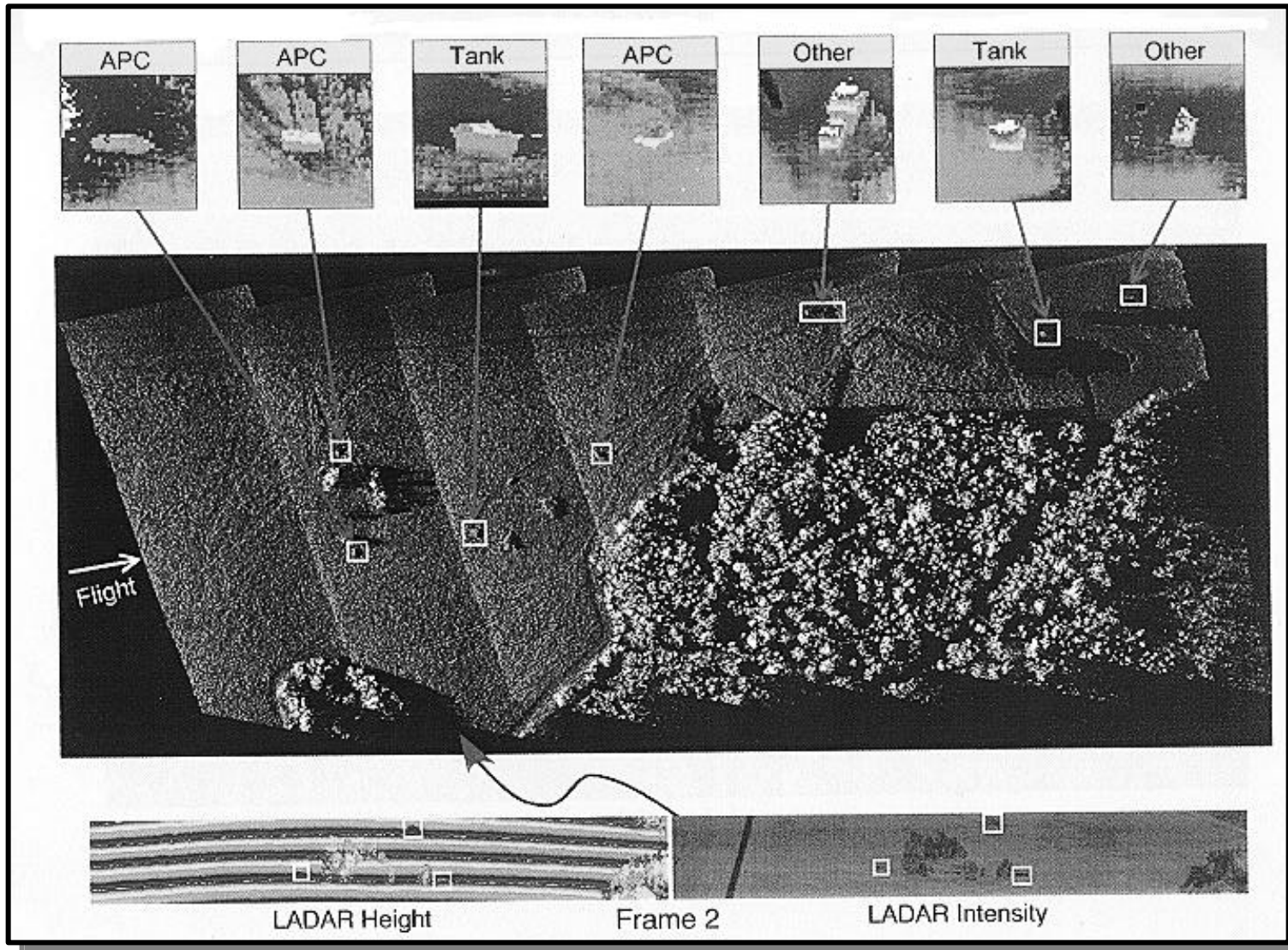


Length	31"
Wingspan	47"
Box size	8"x10"
Weight	85-95 lbs

Multi-mode Warhead

- Optimized Lethality
- Minimize Collateral Damage

LADAR Automatic Target Recognition Captive Flight Test Results



Notional Weather Sensors & Data



Thermometer/
Hygrometer



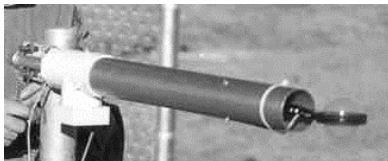
Anemometer



Ceilometer



Visibility /
Precip Type



Radiometer



Digital Camera

Standard Measurements (all sites):

- Temperature / Humidity
- Wind Speed and Direction

Also at Primary Stations:

- Cloud amount and ceiling height
- Visibility
- Precipitation rate and type
- Solar radiation
- Visible camera image

Data Rates:

- Primary sites: 1-sec sampling, 1-min avg
- Remote sites: 5-sec sampling, 5-min avg, 15-min data collection

Data Assimilation and Fusion

Global/Mesoscale/Tactical/Nowcast

NOGAPS:

- FNMOC spectral model, T159/L24
- Data assimilation; 0-10 day guidance
- Provides boundary conditions for COAMPS coarse mesh

COAMPS:

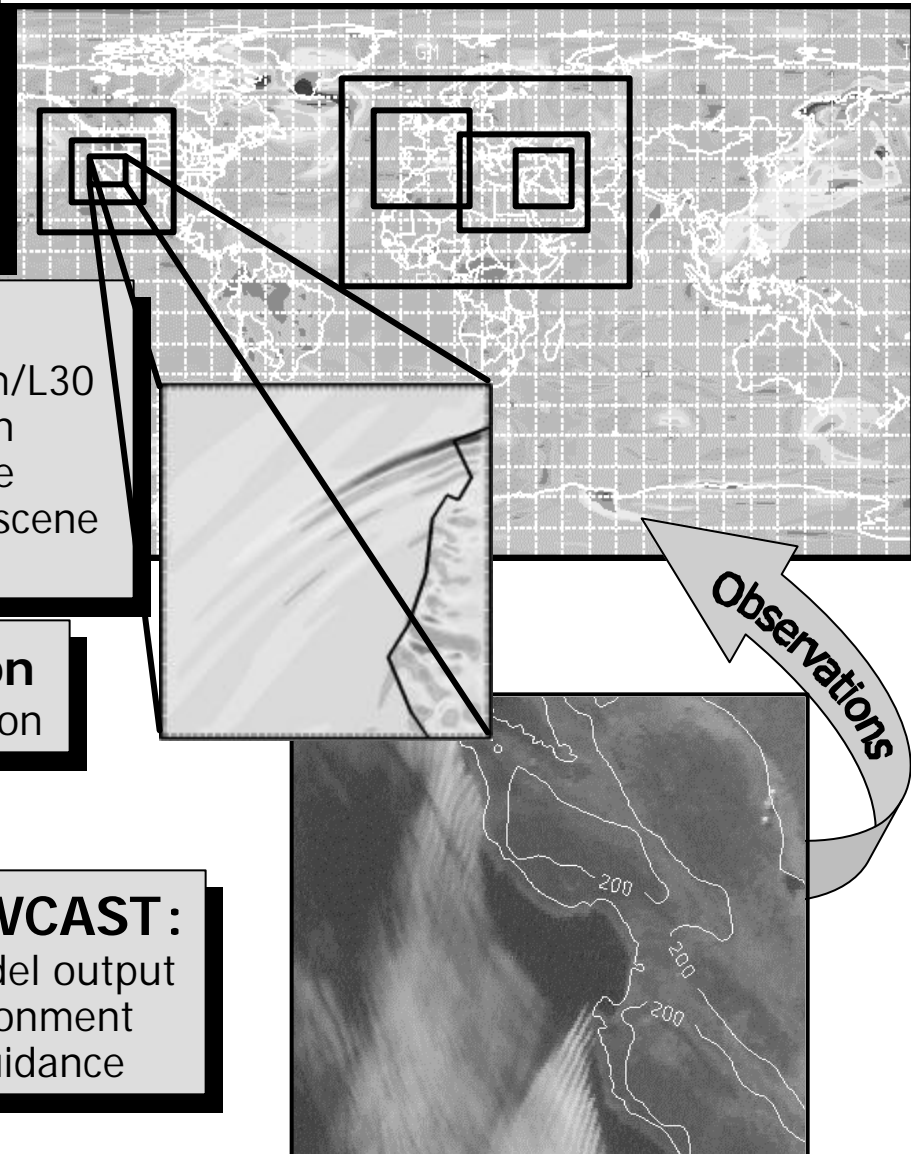
- FNMOC nonhydrostatic model, <9 km/L30
- Globally relocatable; Data assimilation
- Explicit moist physics; 0-72h guidance
- Provides boundary conditions for on-scene COAMPS coarse mesh

TAMS/RT: 3 km resolution

- On-scene tactical data assimilation

WEATHER WEB NOWCAST:

- Fuse observations and model output
- Common battlespace environment
- Tactical end users; 0-6h guidance



An Adams Business Media Publication

January 1999

MEDICAL EQUIPMENT DESIGNER

DENTAL
ORTHOPEDIC
ELECTRO MEDICAL
SURGICAL/MEDICAL
IMAGING/DIAGNOSTICS

The Digest of Medical Design Engineering News
www.medicaldesigner.com

"Pill-Sized" transmitter
to monitor at-risk pregnancies



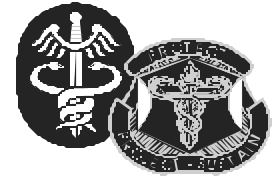
Editor's Choice
high-resolution display panel



Medical Products
motors & drives



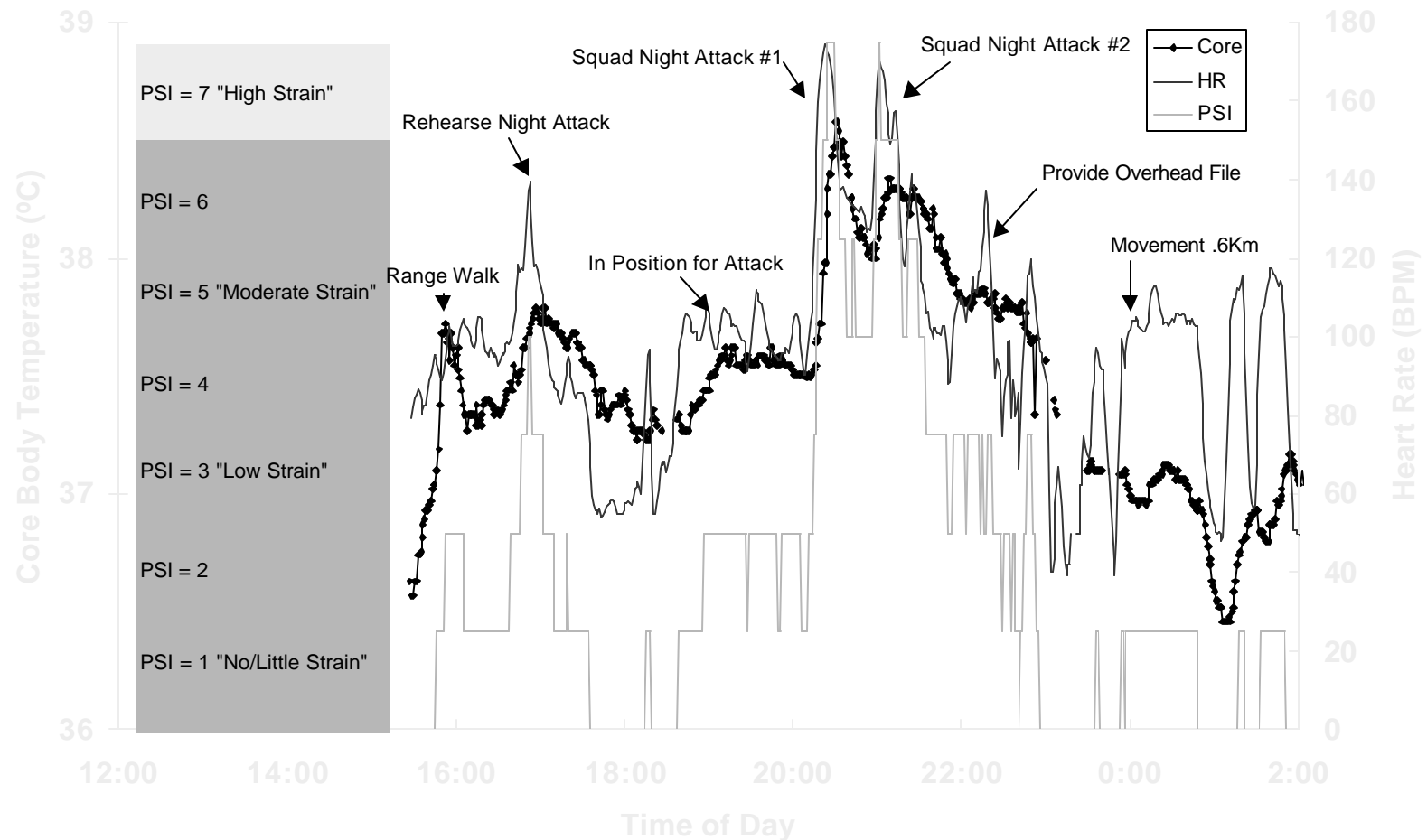
Warfighter Physiological Status Monitoring



Marine Data - September 1999

Physiologic Stress Index (Subject 12, Load 126.6 Kg, Sept 8 - 9 1999)

(Am. J. Physiol. 275(44):R129, 1998)

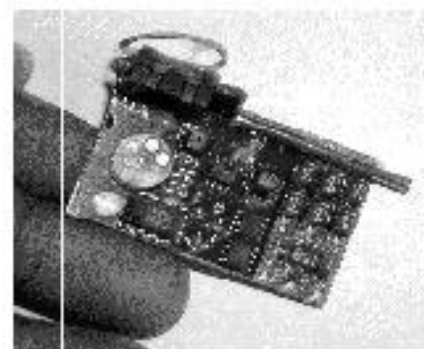




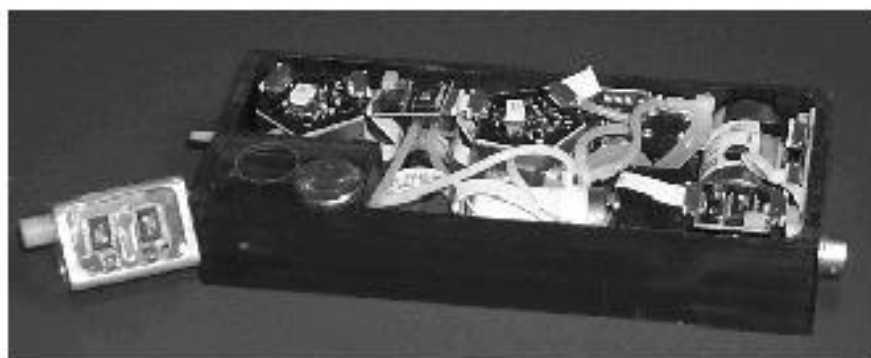
Prototype NRL Chemical Agent Detectors



“Badge Dosimeter” Format

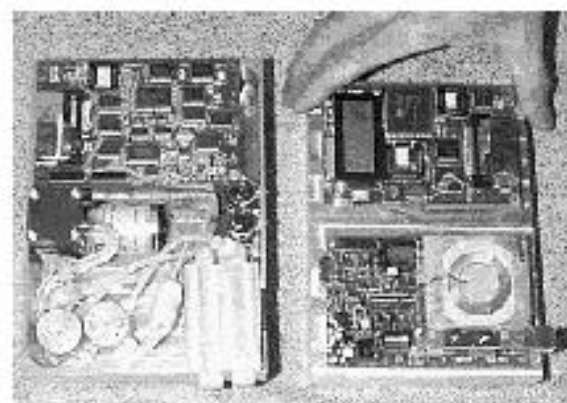


**NRL-BEAGLETTE
“Toss-&-Seek Applications”**

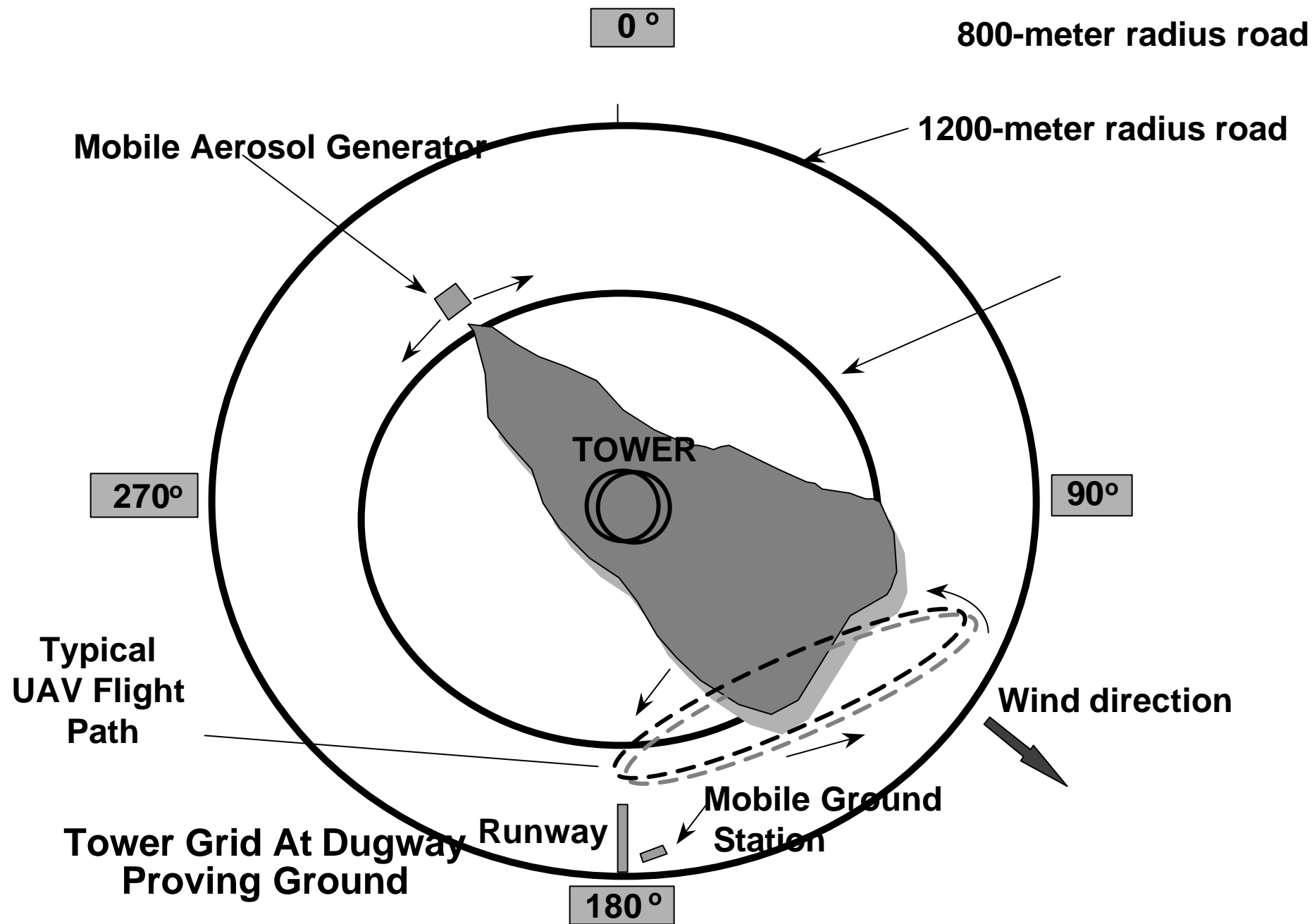


**NRL-CANARY II
UAV/Ground Applications**

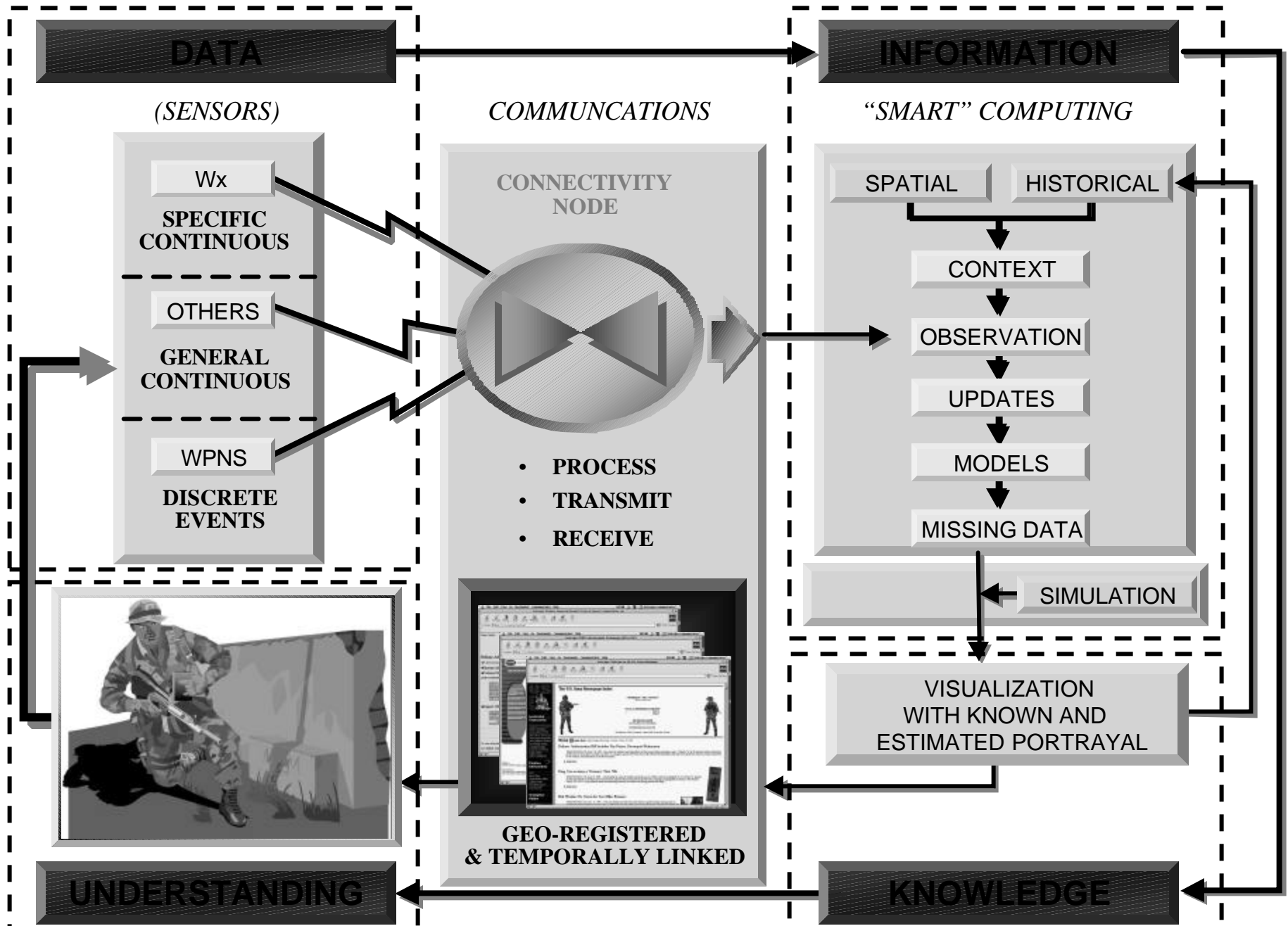
P.O.C: R. Andrew McGill
NRL MS&T Division, Code 6375
Tel: 202-767-0063
Email: amcgill@ccf.nrl.navy.mil



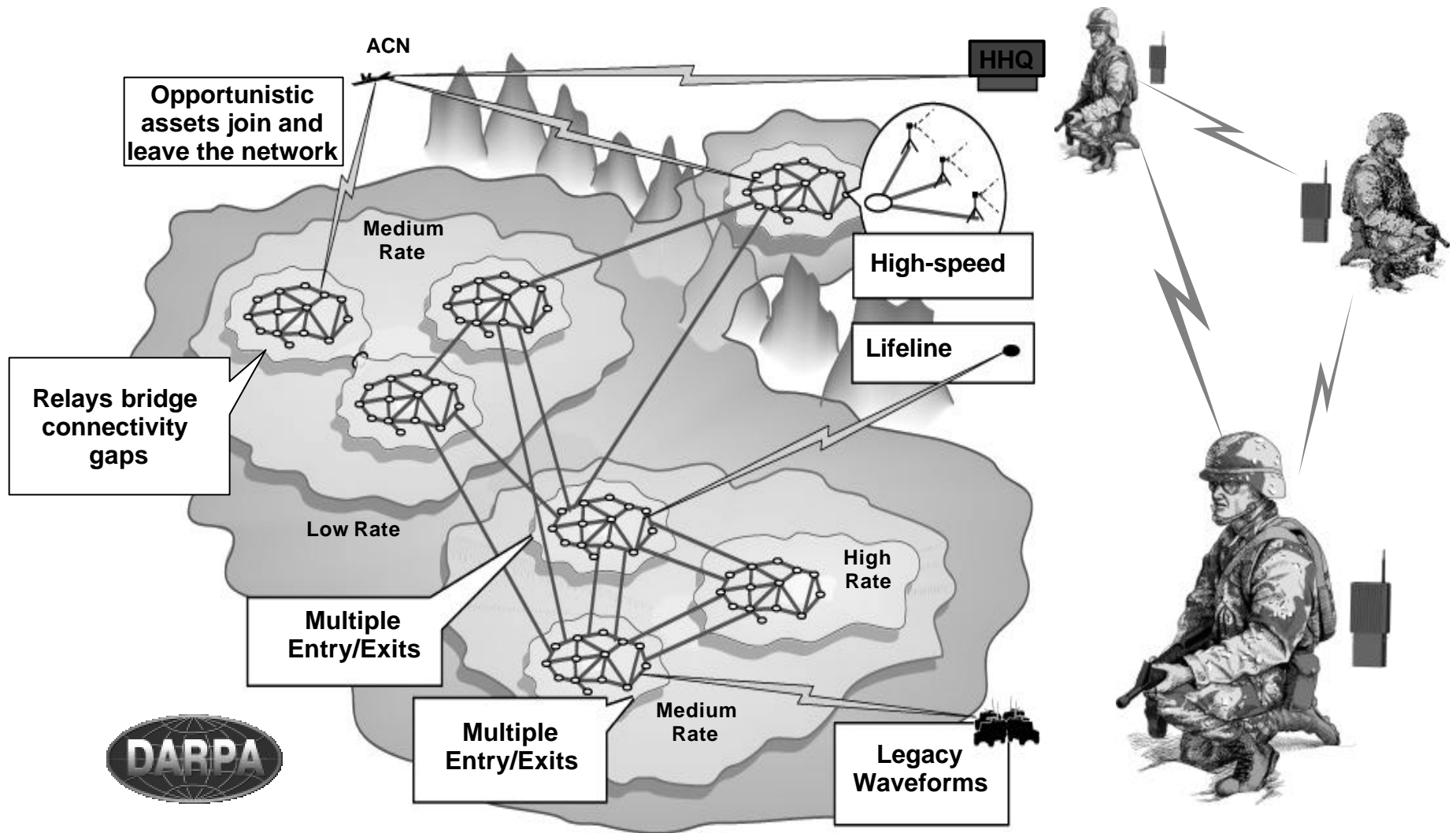
**ISCAD (IMS-SAW CAD)
Binary Detector/UAV Compatible
Ultra Low False Alarm**



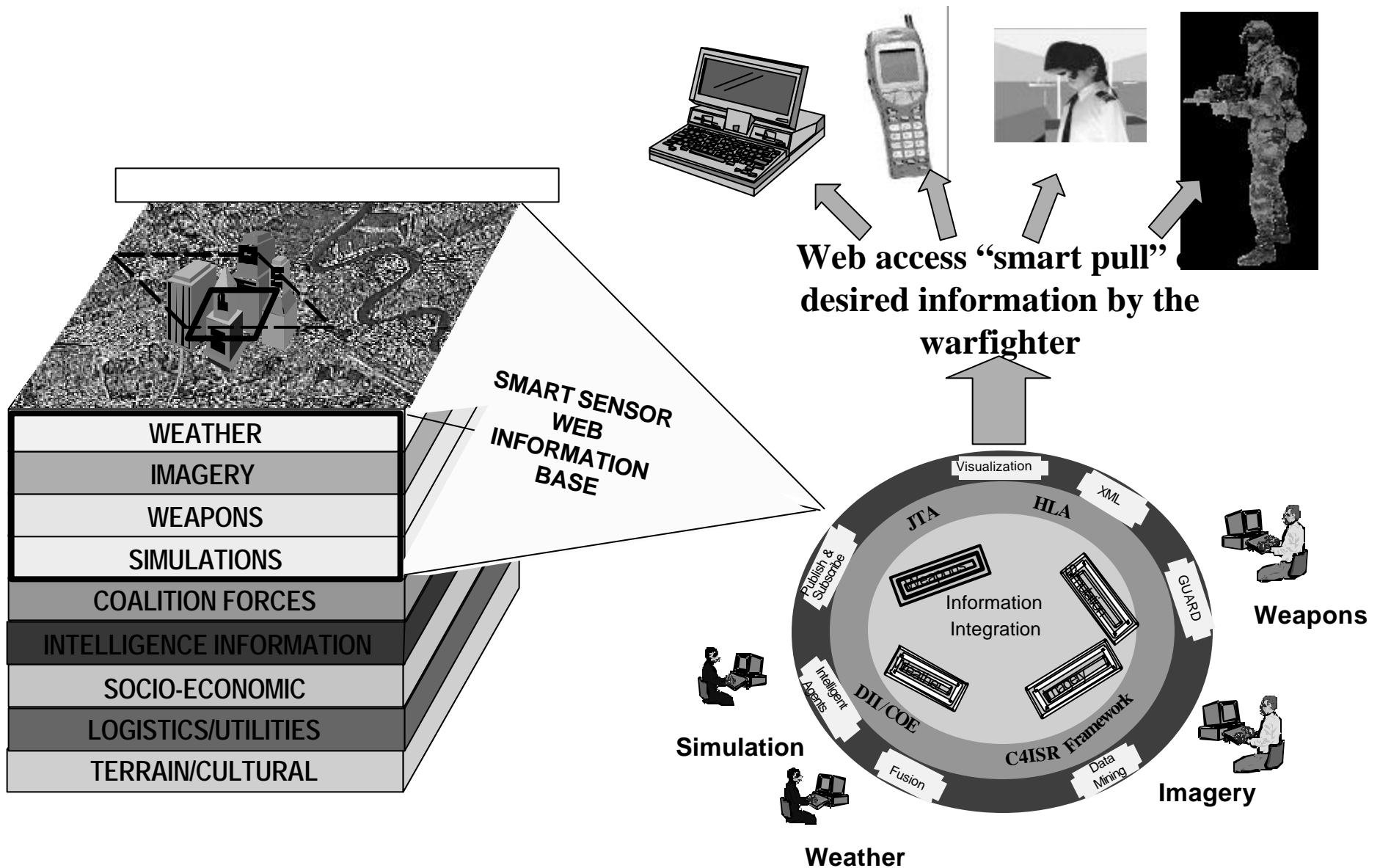
Model of Smart SensorWeb



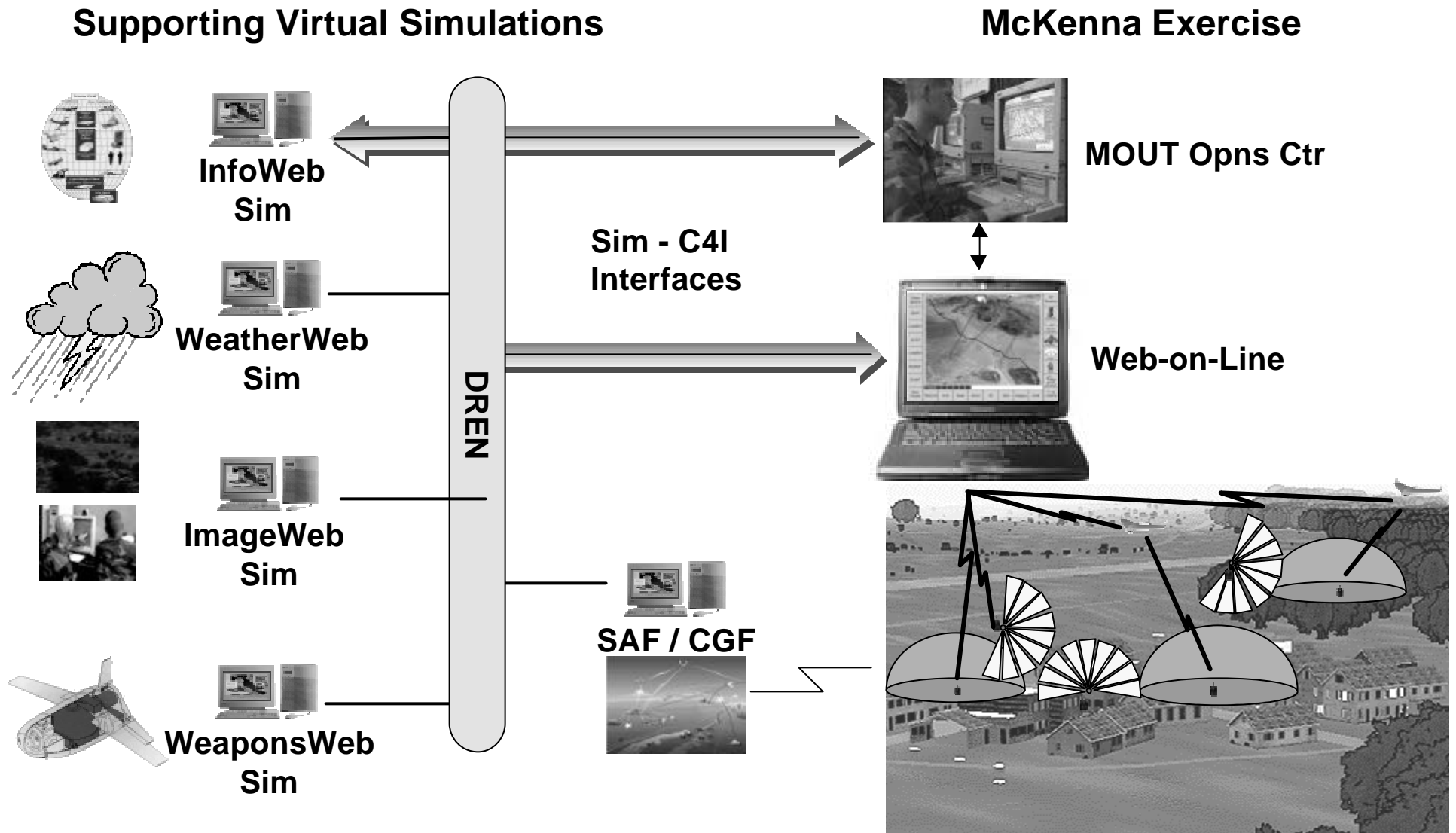
SUO-SAS



Integrated Information Concept



SSW Simulation Testbed Integration Concept



SOF UAV's



Maverick



Pointer



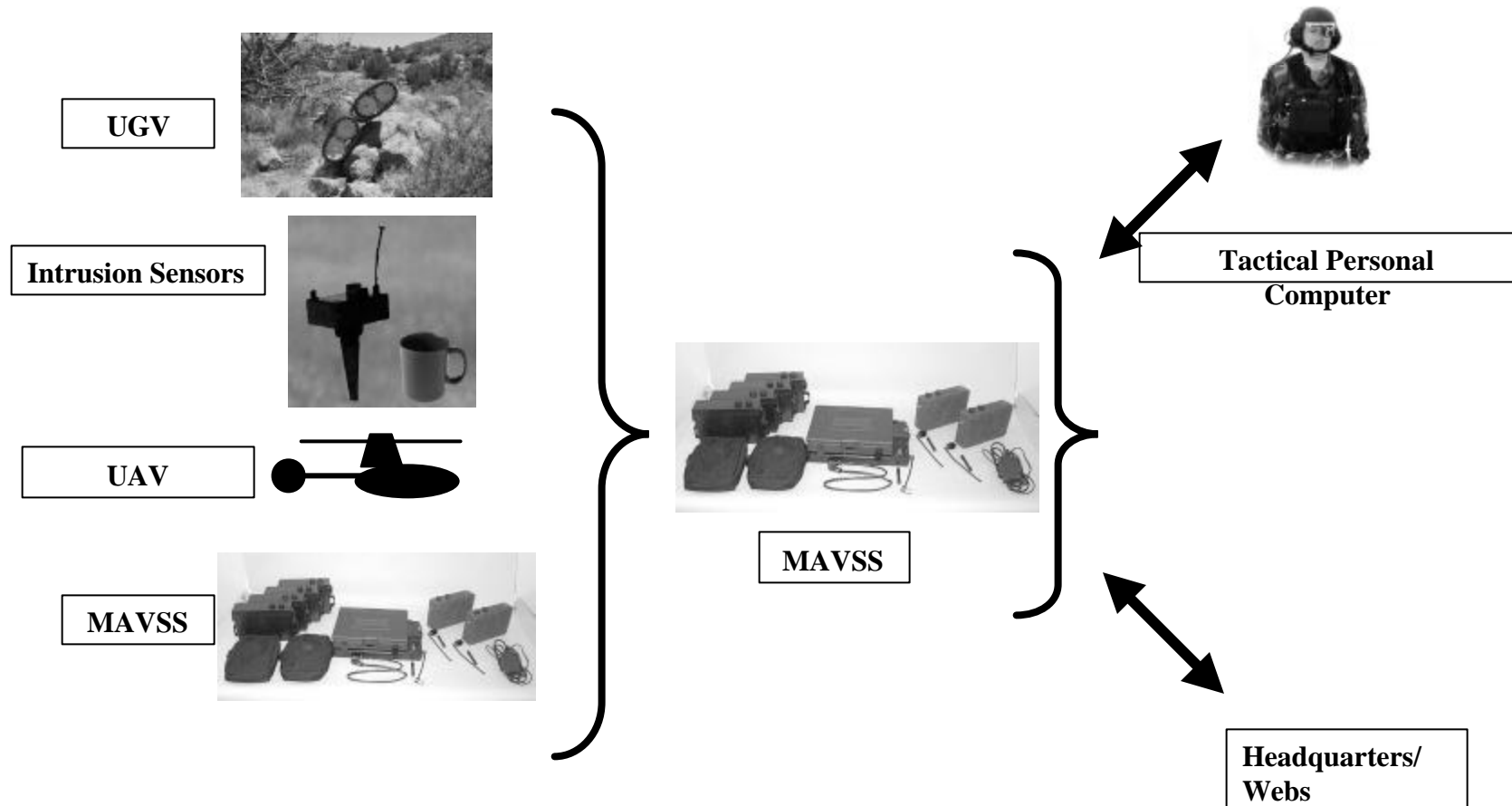
UF MAV

SOF Web

Sensors/ Platforms

Collection/Processing

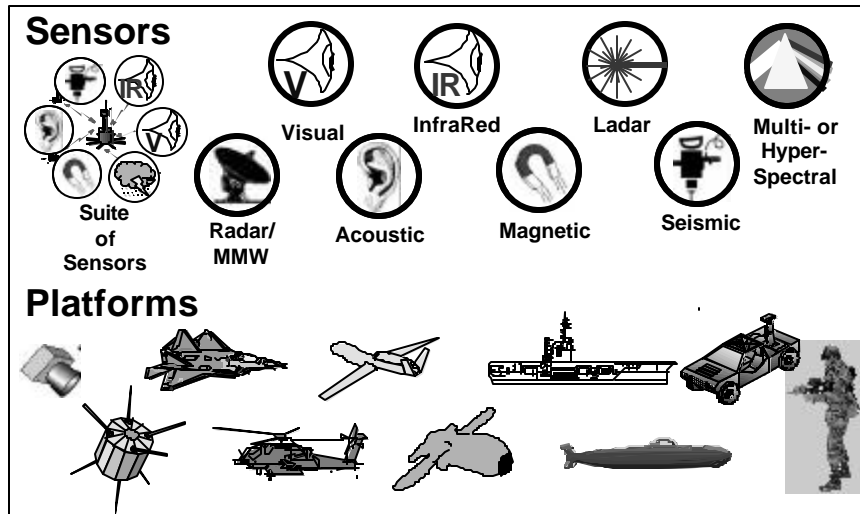
Users



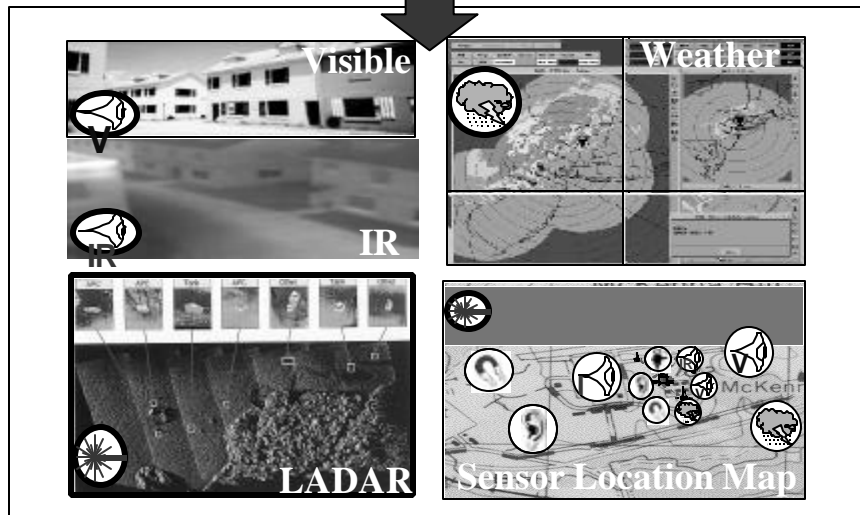
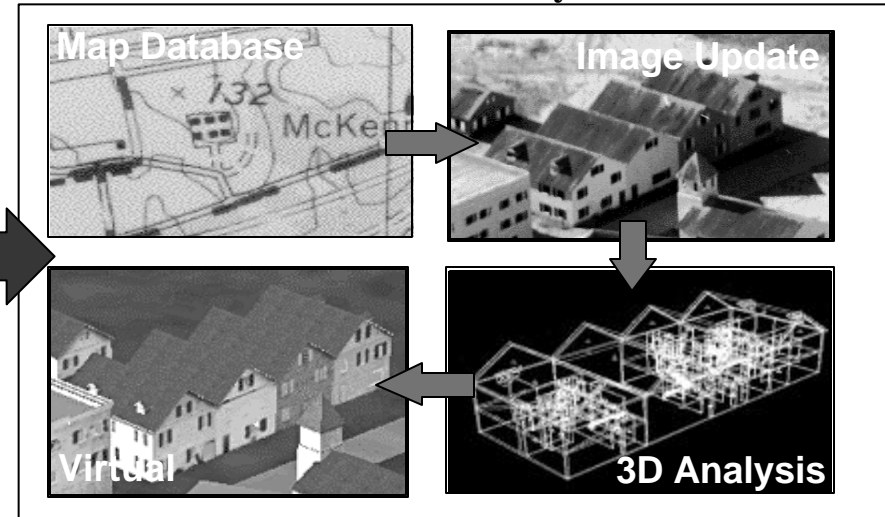
Base SSW Concept

Smart SensorWeb

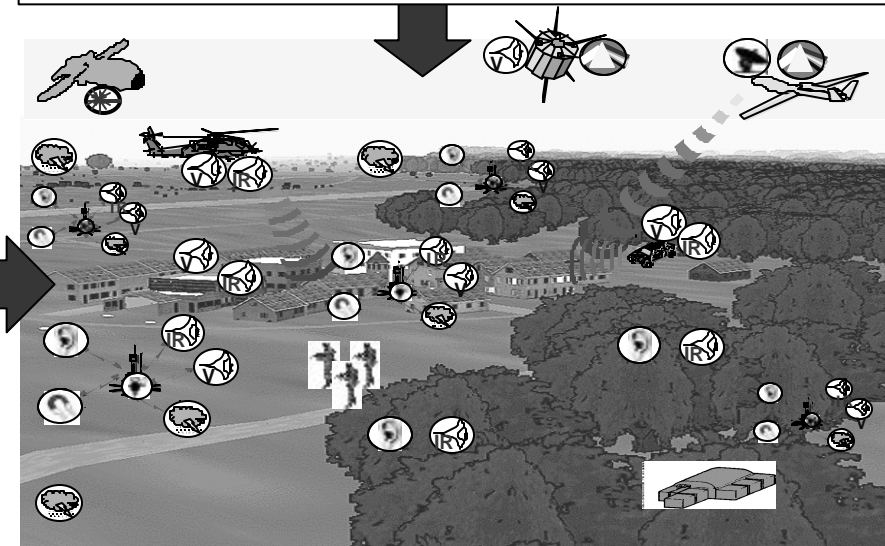
- Collection - Sensors & Platforms



- Computation - Retrieval & Analysis



Display & Visualization - Connotation -



Integrated, Continuous, Local, Sensor Collection - Concept -

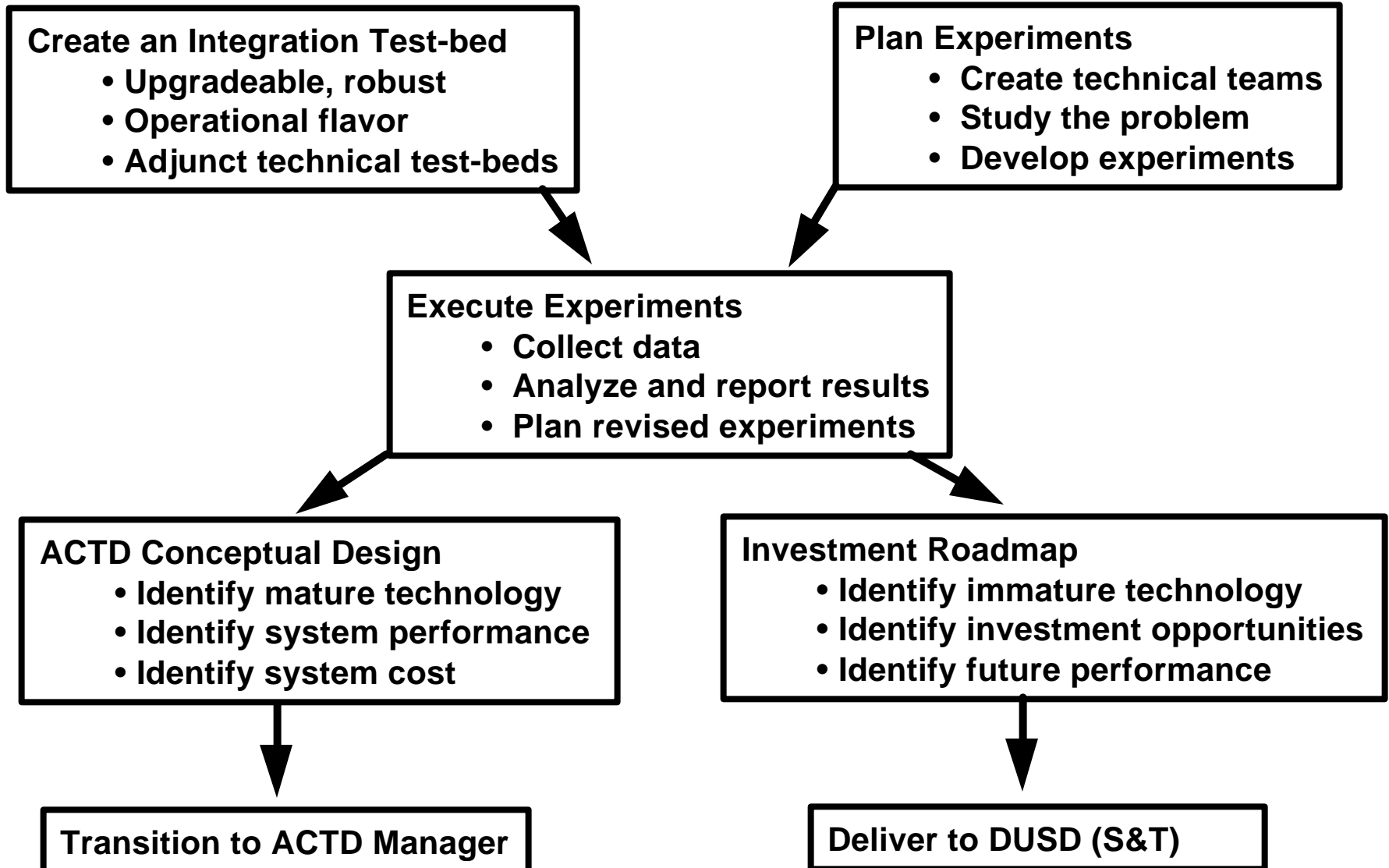
Notional Objective System

Echelon	Sensors	Communications	Database & Processing	Information Visualization
Individual Soldier	<ul style="list-style-type: none"> Ported Wireless Visible & IR camera 	<ul style="list-style-type: none"> Body WLAN Throat to Text Commo 	<ul style="list-style-type: none"> Local video compression 	<ul style="list-style-type: none"> Earphone Miniaturized /eye-mounted display
Fire Team	<ul style="list-style-type: none"> Toss able Local wireless visible and IR cameras 	<ul style="list-style-type: none"> Local Low-Medium bandwidth data link 	<ul style="list-style-type: none"> Local video Compression & force disposition VSAM 	<ul style="list-style-type: none"> Personal display
Squad	<ul style="list-style-type: none"> Emplace able mid-range wireless video & acoustic sensors 	<ul style="list-style-type: none"> Local Medium bandwidth data link 	<ul style="list-style-type: none"> Local video compression & force disposition VSAM 	<ul style="list-style-type: none"> Personal Display
Platoon	<ul style="list-style-type: none"> UGV & Emplace able long-range video & acoustic sensors 	<ul style="list-style-type: none"> Medium-High bandwidth data link 	<ul style="list-style-type: none"> Local video compression , force disposition & status update VSAM 	<ul style="list-style-type: none"> Personal Display
Company	<ul style="list-style-type: none"> UAV & UGV 	<ul style="list-style-type: none"> High bandwidth data Link 	<ul style="list-style-type: none"> Local video compression & multi-sensor fusion VSAM 	<ul style="list-style-type: none"> Mobile TOC
Battalion	<ul style="list-style-type: none"> Multiple UAV & UGV Displaced Acoustics 	<ul style="list-style-type: none"> High bandwidth data Link 	<ul style="list-style-type: none"> Local & external Information Fusion VSAM 	<ul style="list-style-type: none"> Fixed TOC

Additional Sensor Functions

- **ChemBio**
- **Physio-Med**
- **Logistics/Maint**
- **Commo**
- **Location**
- **Weather**
- **Weapons**
- **Others**

Program Execution



Experiment Plan

The System Driver



Experiment # 1

Value of the

Information Products
Assess each product:

- Very useful
- Useful
- Somewhat useful
- Not useful

The Functional Components

Experiment # 2

Information Architecture

- Assess needed bandwidth
- Assess various protocol

Experiment # 3

Sensors

- Assess power constraints
- Assess low cost sensors

Experiment # 4

Data Processing

- Assess ATRs, distributive processing
- Assess collaborative sensors
- Sensor/information fusion

Experiment # 5

Information Visualizations

- Assess product usefulness as function of interface
- Demonstrate simulation/live sensor fusion

Key Integrated System Issues (Optional)

Experiment # 6

Mobility

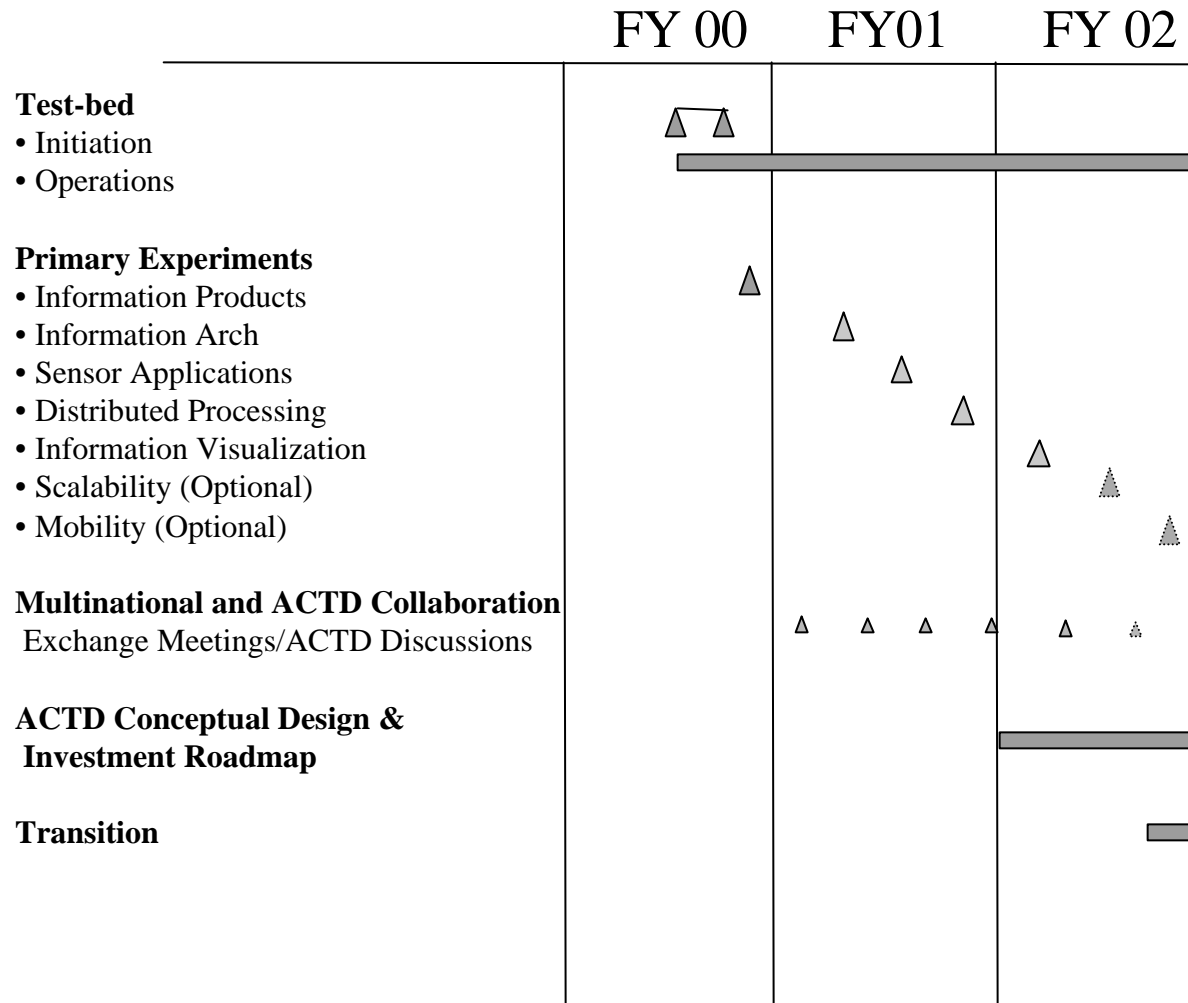
- Assess capability to enter unprepared terrain
- Demonstrate ability to rapidly simulate unprepared area

Experiment # 7

Scalability

- Assess issues associated with full battalion operations
- Demonstrate high resolution large battalion simulation

Revised Program Schedule



SSW Participants

- Army
 - ARL,
 - ARIEM,
 - TMDE,
 - TEC,
 - NVESD,
 - CECOM,
 - ARO,
 - Dismounted Battlespace Battlelab
- Air Force
 - AFRL/Eglin
 - AFRL/Rome
- Navy
 - NRL,
 - ONR,
 - SPAWAR,
 - OPNAV,
 - NAWCWD
- USMC
 - MCWL
- FFRDC
 - Lincoln Labs,
 - IDA,
 - SEI
- SOCOM
 - OST
- DARPA
 - SUO-SAS
 - SensIT
 - VSAM
- DMSO
- DTRA
- Industry
 - Casio
 - Sony
 - McQ

International: Germany, Sweden, England, Canada, & Australia

Next meeting 24-26 October, Lake Constance, Germany

Leveraged Efforts

Program Elements and Project Codes

ImageWeb

Army WEBS

Army APLA

Airborne Sensor Platforms

WeatherWeb

Atmospheric Investigations

Battlefield Environment & Signature Research

University Partnering for Operations [Ar & AF]

WeaponsWeb

Powered LOCAAS ATD

Cruise Missile Real-Time Retargeting

SimulationWeb

Integrated Sensor Modeling and Simulation

Antipersonnel Landmine Alternatives

Joint Countermine ACTD Simulation

Information IntegrationWeb

Consistent Battlespace Picture

Joint Battlespace Infoshpere

METOC Architecture Study

Dynamic Database

General Intelligence Processor

High Performance Computing

Global Awareness Virtual Testbed

JCS/J6V Multi-National Engineering Effort

SUO/SAS

Technology Transfer Mechanisms

MURIs

13 Projects

SBIRS

10 Subjects: 6+ Proposals Each

APBI: Commercial Solicitation

24 Companies

47 Proposals

10 Further Reviewed

5 Funded

Involvement in Ongoing ACTDs

Military Operations in Urban Terrain

Personnel Recovery

Pathfinder

CEASAR (Potential)

DARPA Programs

SUO-SAS

SenseIT

VSAM

ACTDs

- Involvement in Ongoing ACTDs
 - Military Operations in Urban Terrain
 - Personnel Recovery
 - Pathfinder
 - CEASAR (Potential)
- SSW Working Group
 - ACTD Staff
 - Services
 - JFCOM, SOCOM
 - SSW Staff
- Possible Outcomes
 - Stand-alone ACTD
 - Multiple ACTD efforts
 - Support existing ACTDs
 - ATD

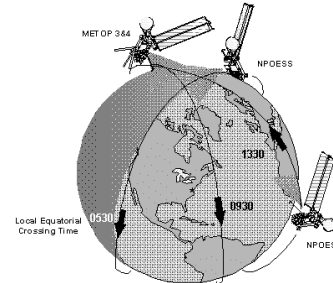
DoD S&T is a Partnership

**Stable, Long Term
Investment**



Service Labs

Expanded Resource Base



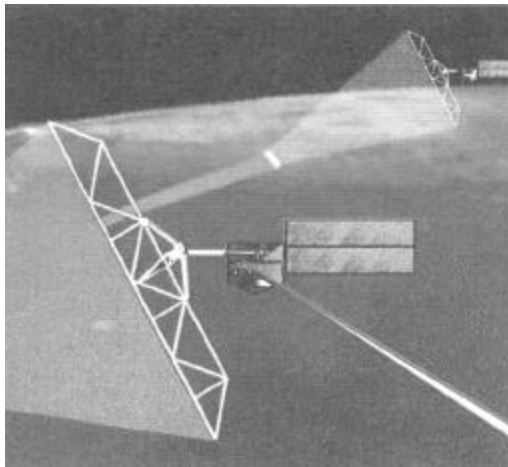
Interagency

New Ideas, Knowledge



Universities

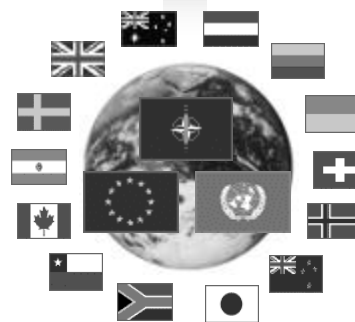
DARPA



High Risk, High Payoff

**Maximum National
Security Payoff**

International



Coalition Capability

Industries



Innovation, Transition

*Technical Superiority is
Critical for National Security.*

*In peace, it provides deterrence;
In crisis, it provides options;
In war, it provides an edge.*

